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Off-Design Exergy Analysis of Convective Drying Using a Two-Phase Multispecies Model

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Abstract: The design of a convective drying cycle could be challenging because its thermodynamic performance depends on a wide range of operating parameters. Further, the initial product properties and environmental conditions fluctuate during the production, affecting the final product quality, environmental impact, and energy usage. An off-design analysis distinguishes the effects of different parameters defining the setup with the best and more stable performance. This study analyzes a reference scenario configured as an existing system and three system upgrades to recover the supplied energy and avoid heat and air dumping in the atmosphere. We calculate their performance for different seasons, initial product moisture, input/output rate, and two products. The analysis comprises 16 simulation cases, the solutions of a two-phase multispecies Euler–Euler model that simulates the thermodynamic equilibrium in all components. Results discuss the combination of parameters that maximizes the evaporation rate and produces the highest benefits on global performance up to doubling the reference levels. The advantages of heat recovery vary by the amount of wasted energy, increasing the exergy efficiency by a maximum of 17%. Energy needs for air recirculation cut the performance at least by 50%. Concluding remarks present the technical guidelines to reduce energy use and optimize production.

Keywords: drying; energy analysis; exergy analysis; multiphase model; multispecies model; thermodynamics

1. Introduction

Thermal drying plays a crucial role in several industries, such as chemical, pharmaceutical, agricultural, and food production. It involves heating a wet product to evaporate its liquid fraction and generating a thermally induced mass flux [1]. According to the dominant energy transfer mechanism, thermal drying can be categorized into convective [2], conductive [3], and radiative drying [4]. The present study focuses on convective drying operated as a continuous process on a horizontal fluidized bed (Figure 1).

The fluidized bed systems present several advantages as a good mixing quality (homogeneous temperature distribution along the bed) and high heat and mass transfer rate caused by the extended contact surface between the solid particles, and the gaseous phase [5,6]. However, reaching the optimal thermodynamic performance of such systems needs careful tuning of numerous operating parameters that influence the final energy consumption, product quality, and environmental effects.

For example, the finest particles (powder) tend to agglomerate, affecting the evaporation rate and quality of the final product [7]. This effect increases the bed pressure drop; thus, a faster airflow becomes necessary to preserve product quality, but it increases the final energy consumption, and costs [8]. Further limitations of the global performance derive from the unavoidable inefficiencies of the process: the sensible heating of the dry fraction, the heat losses of the drying chamber, and the low thermal conductivity of the heat transfer media (air), which demands high operative temperatures to drive adequate heat



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Copyright: © 2020 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https://creativecommons.org/licenses/by/4.0/). flux [9]. Another issue regards the effect of the environmental conditions on the final energy use: the analysis of Reference [10] reveal the drying chamber as particularly susceptible to the external temperature; its performance deteriorate with temperature fluctuations of approx. 5 °C. Finally, some specific applications such as the convective drying of biomass and hazardous materials, release several pollutants into the atmosphere; this deteriorates local air quality and contributes to greenhouses gas emissions [11–13]. For such reasons, stringent environmental regulations limit their functioning.



Figure 1. Fluidized bed drying chamber: (1) product inlet; (2) air inlet; (3) air diffuser; (4) conveyor belt; (5) insulated wall; (6) air outlet; and (7) product outlet.

In the design and optimization practice, predicting all the effects mentioned above can be challenging because of the relations among the drying parameters and the mutual dependencies among the system components [14]. The standard approach studies the relation between the drying conditions and final performance by the energy analysis of the drying chamber. Dincer et al. [15] calculated the efficiency of the cycle (i.e., drying efficiency) as the ratio between the energy invested in the evaporation process over the total energy entering the drying chamber by hot airflow. Further studies [16] included the specific energy consumption, calculated as the amount of consumed energy per unit mass of the evaporated moisture.

Energy analysis by itself cannot calculate the operative costs and any form of environmental effect because it does not distinguish the primary energy source; such an approach does not provide any information regarding the effects of the climate on system productivity. To overcome these limitations, several authors included the exergy analysis in the evaluation of system performances.

The first exergy analysis of convective drying is presented in Reference [17], wherein the authors calculate the exergy efficiency of the drying chamber as the ratio between the exergy invested in the evaporation process to the total exergy of the entering airflow. Assuming the entering product is at a dead-state, the exergy investment is the exergy of the total evaporated moisture leaving the drying chamber. Several works follow the approaches presented above. Akpinar et al. [18] related the energy utilization of the drying chamber with an evaporation rate and initial product moisture; they measured an increase in exergy losses using the drying air temperature and velocity. Yogendrasasidhar et al. [19] analyzed the effect of the several drying parameters on the energy utilization, exergy losses, and exergy efficiency of the system: by increasing the wall temperature and air velocity, the energy usage augments but the exergy losses decreases with benefits on the final exergy efficiency; the prolonging of drying time produces a two-fold benefit by reducing energy usage and exergy losses and by increasing exergy efficiency. Aviara et al. [20] showed a linear dependence between energy efficiency and the drying air temperature.

More recent research on convective drying oriented the exergy analysis toward optimization by comparing different system configurations and operative conditions. Icier et al. [21] compared the exergy performance of two open drying cycles and a closed cycle, where drying air was recovered from the drying chamber and heated by a heat pump. Xiang et al. [22] analyzed a drying system coupled to a heat pump; in particular, they investigated how the system performance changes under different operative conditions, varying the amount of recirculating air (from an open to a fully-closed cycle). Cay et al. [23,24] analyzed and compared two open cycles, in which internal and external combustion chambers heat the drying air, respectively. Erbay [10], and Gungor [25] investigated how dead-state temperature affects the exergy performance of a drying system fed by a ground source and a gas heat pump.

All studies presented above refer to the given system configurations; their results are valid only under the working conditions observed for the analyzed system and can be used for designing the drying cycle of a specific material. Furthermore, limiting the performance analysis to the drying chamber misses the most recent and accurate optimization techniques of energy systems that extend the exergy analysis to a multicomponent level (they calculate the exergy destruction in a single component by considering interdependencies with all other components) [26,27]. Thus, the research gap in the current literature is based on the design approach specifically formulated for convective drying, which considers the effects of changing the system configuration and operative conditions (e.g., dry another product, adding another component, and varying the climate) for the optimization of thermodynamics and costs [28].

The design of a drying system needs a theoretical model to calculate the state of working flows in the different components (i.e., thermodynamic equilibrium model). The Euler–Euler description is a common approach to simulate the thermodynamic equilibrium of a drying process due to its low computational costs and the capability to simulate fluids with a high concentration of the dispersed phase [29-31]. Assari et al. [32,33] studied the drying of wheat grain: first, they formulated a two-fluid model to investigate the effects of varying the operative conditions on the main operative parameters of the drying bed (e.g., void percentage and air humidity); in the following study, they analyzed the exergy performance. Li et al. [34] modeled two fluids, the bubbly and emulsion phases, a mixture of an interstitial gas, and a solid phase; using this formulation, they performed a sensitivity analysis of the drying performance with respect to the state of inlet air, particle diameter, and wall temperature of the drying chamber. Ranjbaran et al. [35] developed a two-fluid model for paddy drying; they investigated the temporal variation of the energy and exergy efficiency during the drying process with effects of air temperature and flow rate; a source term in transport equations is used to model the evaporation of moisture. Rosli et al. [36] simulate the drying of sago waste by a two-fluid model of the drying column; they investigate by CFD the effects of different drying conditions (e.g., the air velocity, temperature, and particle size) on the fluidization of the bed. Jang et al. [37] simulate a fluidized bed dryer by an Euler-Euler model coupled to empirical correlations representing the inter-phase exchanges; the authors investigate the advantages of such a model in the design and scaling-up of pharmaceutical applications.

The above studies simulated the drying process by two homogeneous phases—the drying air and the wet solid—without focusing on their chemical composition. A multispecies approach enhances the versatility and accuracy of the two-fluids theory—it comprehends the effects of each species on the mass and energy fluxes [38]. Furthermore, this approach can simulate applications of reactive flows according to the stoichiometry of the ongoing chemical reactions (e.g., combustion of a hydrocarbon for air heating). The multicomponent theory generally finds applications in petroleum distillation [39,40], while the available literature lacks references for applications to convective drying.

In addition to the thermodynamic equilibrium model, the design of a drying system needs characteristic equations describing the heat and mass transfer phenomena that occur in each component; as an example, the characteristic equation of the drying chamber is the evaporation model. Defraeye et al. [41] derive the characteristic equation of drying by a theoretical approach—the authors analyze the convective drying of a porous flat plate by solving the transport phenomena at the interface between the porous media and the airflow, explicitly. Such an approach, known as conjugate modeling, describes in detail the physics of the heat and mass transfer; however, despite its accuracy, just a few academic applications use this technique because of the high complexity, and computational costs [30]. Quite the opposite, the empirical or non-conjugated models derive from experimental observations and describe the heat and mass transfer by constant coefficients, with a limited understanding of the involved physics. Some well-known examples of empirical models are Newton's law of cooling, and the evaporation model of Page [42].

Our study investigates the thermodynamic performance of convective drying under different operating conditions and system configurations; the final aim is distinguishing the parameters with the most significant effects on the energy use and product quality to define the setup with the best performance. We follow a theoretical approach, named off-design analysis applied successfully for the optimization and control strategies of various energy systems [43–45]. The novelty of our work is the nature of the studied application: in the literature, there is not any off-design analysis of convective drying; in particular, the current design practice lacks a theoretical formulation for modeling the state of working flows in the drying chamber and all system components, including the devices for heat and mass recovery. The level of detail of our theoretical approach is a further innovation in the field of drying modeling: we formulate the two-fluids theory describing the thermodynamic equilibrium of the single chemical species to simulate all components of the drying system. Finally, due to the adaptability of the solving algorithm, we present an innovative tool for both design new drying cycles and verify the states of working flows in existing systems.

The presented equilibrium model includes the multispecies approach in the twofluid theory to simulate all the components of a drying system; in particular, we follow a two-fluid multispecies Euler–Euler (TFMM) approach to simulate the following processes.

- Mass and energy exchange between nonreactive phases: Convective drying of a wet solid and air-water counter-current mixing;
- Mass and energy exchange between reactive phases: combustion of airflow by a hydrocarbon jet;
- *Energy exchange between nonreactive phases:* Air-to-air and air-to-water heat exchange within a tube bank.

Our analysis aims to support the design practice of a drying system rather than investigate drying physics in detail. Thus, we simulate heat and mass exchanges by empirical equations because of their appropriate accuracy for the scale of simulated processes (macro-scale between 0.01–10 m [30]), as well as the advantages of a simple mathematical formulation and low computational costs.

The analysis starts with the exergy analysis of a reference drying cycle, named the baseline scenario, based on an existing industrial system; this scenario mounts the essential components of convective drying: fan, combustion chamber, and drying chamber (Figure 1). We calculate the baseline performance at the operative conditions of the existing system and validate the results against experimental data. Later, we change the drying conditions, dead-state conditions, and dried material to investigate the effects on energy consumption and exergy efficiency. By the last set of operative conditions, we assess the drying of municipal

sewage sludge, thereby aiming to contribute to this crucial but scarcely investigated sector. Finally, we modified the reference system to investigate the effects on the global performance of heat and mass recovery by three different layouts.

2. Research and Method

2.1. Governing Equations

We assume that all thermodynamic processes of a convective drying cycle occur in a one-dimensional open system of infinitesimal dx length (Figure 2). To support the assumption of a one-dimensional system, we calculate the heat and mass exchange rates by the lumped-system model (e.g., the Page model for drying and Newton's cooling law for heat exchangers; see more details in the Appendix A).

The TFMM describes the mass and energy exchanges, entropy generation, and exergy destruction: Phase 1 is drying air, which is a semi-perfect gas mixture; Phase 2 is the substance that exchanges mass and heat with drying air (its state and composition vary by the nature of the simulated process).

Assuming equilibrium between the *j*-species dispersed in the *i*-phase, we track them by their respective mass fractions

N

$$\alpha_i = \frac{m_i}{m_{os}} \tag{1}$$

$$\epsilon_{ij} = \frac{m_{ij}}{m_i} \tag{2}$$

where

$$u_{os} = \sum_{i} m_i \tag{3}$$

$$\sum_{i} \alpha_{i} = \sum_{j} \epsilon_{ij} = 1.$$
(4)



Figure 2. The two-fluid multispecies model of the i-phase formed by the dispersed j-species.

• Mass balance of *j*-species per unit length is

$$\frac{\partial m'_{ij}}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_{ij}) = (\Delta \dot{m}_{12,j})'.$$
(5)

The mass balance of the *i*-phase is obtained by summing the *j*-species as

$$\frac{\partial m'_i}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_i) = (\Delta \dot{m}_{12})'. \tag{6}$$

The term

$$\Delta \dot{m}_{12,j} = -\Delta \dot{m}_{21,j} \tag{7}$$

represents the mass exchange rate between two phases. Energy balance is

$$\frac{\partial E'_{ij}}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_{ij}h_{ij}) = (\dot{W}_{ij}^{\leftarrow})' + (\dot{Q}_{ij}^{\leftarrow})' + (\Delta \dot{H}_{12,j})'$$
(8)

and that for the whole *i*-phase is

$$\frac{\partial E'_i}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_i h_i) = (\dot{W}_i^{\leftarrow})' + (\dot{Q}_i^{\leftarrow})' + (\Delta \dot{H}_{12})'. \tag{9}$$

The terms $\dot{W}_{ij}^{\leftarrow}$ and $\dot{Q}_{ij}^{\leftarrow}$ represent the shaft work and the heat absorbed by the *j*-species (from the environment or other species). The term $\Delta \dot{H}_{12,j}$ is the heat exchanged between two phases by any phase transition and/or chemical reaction

$$\Delta \dot{H}_{12,j} = -\Delta \dot{H}_{21,j}.\tag{10}$$

• Entropy balance is given by

$$\frac{\partial S'_{ij}}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_{ij}s_{ij}) = \left(\frac{Q_{ij}}{T_b}\right)' + (\Delta \dot{S}_{12,j})' + (\dot{S}_{irr,ij})' \tag{11}$$

and that for the whole *i*-phase is

$$\frac{\partial S'_i}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_i s_i) = \left(\frac{\dot{Q}_i^{\leftarrow}}{T_b}\right)' + (\Delta \dot{S}_{12})' + (\dot{S}_{irr,i})'.$$
(12)

The entropy generated by $\dot{Q}_{ij}^{\leftarrow}$ depends on the system boundary temperature T_b , whereas $\dot{S}_{irr,ij}$ is the entropy generated by process irreversibilities; the term $\Delta \dot{S}_{12,j}$ represents the entropy related to any phase change of the *j*-species:

$$\Delta \dot{S}_{12,j} = -\Delta \dot{S}_{21,j}.\tag{13}$$

• Exergy balance is given by

$$\frac{\partial Ex'_{ij}}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_{ij}ex_{ij}) = (\dot{W}_{ij}^{\leftarrow})' + (\dot{Q}_{ij}^{\leftarrow})'\left(1 - \frac{T_0}{T_b}\right) + (\Delta \dot{E}x_{12,j})' - (\dot{E}x_{d,ij})'$$
(14)

and the contribution for the whole *i*-phase is

$$\frac{\partial Ex_i'}{\partial t} + \frac{\partial}{\partial x}(\dot{m}_i ex_i) = (\dot{W}_i^{\leftarrow})' + (\dot{Q}_i^{\leftarrow})' \left(1 - \frac{T_0}{T_b}\right) + (\Delta \dot{E}x_{12})' - (\dot{E}x_{d,i})', \quad (15)$$

where T_0 is the dead-state temperature. The exergy exchange $\Delta E x_{12,j}$ and the exergy destroyed by process irreversibility $E x_{d,ij}$ are

$$\Delta \dot{E}x_{12,j} = \Delta \dot{H}_{12,j} - T_0 \Delta \dot{S}_{12,j} = -\Delta \dot{E}x_{21,j}$$
(16)

$$\dot{E}x_{d,ij} = T_0 \dot{S}_{irr,ij}.$$
(17)

In the following sections, we assume steady-state conditions, and therefore, all time derivatives $\frac{\delta}{\delta t}$ are equal to zero.

2.2. Solving Algorithm

A custom-developed code written in C language is used to solve the TFMM balance equations. The algorithm (Figure 3) consists of modules connected by one or more dataflows (representing matter and energy streams). There is a node between two connected modules.

A module is a function block that uses the upstream node values as input and calculates the state of the *i*-phases at the downstream node as a result; each module includes the following parts:

- 1. TFMM governing equations;
- 2. State equation of the i-phase;
- 3. Component characteristic equations;
- 4. End-of-file (EOF) values.



Figure 3. Solving algorithm applied to the baseline scenario.

The Part 1 is the general equilibrium model and it is unvaried in all modules; Part 2 depends on the nature of the *i*-phases entering/leaving the module, and it defines the coefficients of TFMM differential equations (e.g., perfect gas or incompressible fluid, constant or polynomial specific heat); Parts 3–4 are strictly related to the features of the simulated component, and they are different for each module.

The advantage of such a structure is the high adaptability of its running logic, which is suitable for both design and off-design analysis of energy systems. Following the equations of Parts 2–3, the function block implicitly solves Part 1 under a steady state using the Newton–Raphson method [46]. This procedure is an iterative process that produces

a sequence of solutions for consecutive dx space intervals; it stops when the solution matches the target values (design) or when the total number of solved intervals equals the component dimensions (off-design), both fixed by Part 4. The ideal gas law is the equation of state used in this analysis. State functions are calculated by a polynomial T-dependent specific heat for gaseous species and a constant specific heat for liquid and solid species ([47–49]). Further details about state equations, component-specific equations (Part 3), and design targets (Part 4) are in Appendix A.

3. Case Study: Baseline Scenario

The case study of the current analysis is an industrial drier located at Kedah, Malaysia; this system, designed to dry rice paddy, involves three centrifugal fans (maximum capacity of each: 15 kW) and a furnace to heat the drying air at the operative temperature; the drying chamber is a fluidized bed system (Figure 1).

The bed dimensions l_x , l_y are 4.85 m and 0.97 m; the bed thickness l_z varies based on the operative conditions. However, we assume it is equal to 0.1 m according to most experimental observations [50,51]. The baseline scenario (Figure 4) reproduces the case study. This configuration is the benchmark of our analysis because it runs the fundamental steps of convective drying: a fan flows the external air to the combustion chamber; the combustion chamber heats up the drying air at the set temperature (T_H); and the heated air enters the drying chamber, where the drying process takes place as cross-flow heat and mass exchange.





Figure 4. Baseline scenario corresponds to the layout of the case study.

4. Validation of TFMM

The validation estimates the accuracy of TFMM for simulating the case study; it compares the model predictions to the experimental data of two works ([50,51]) that describe the functioning of the reference system at different seasons and under different operating conditions. The numerical comparison focuses on two parameters that strictly depend on the mass and energy balance of the drying process:

- 1. Final moisture content of the dried product (u_f) , which indicates the total evaporated moisture (i.e., evaporation rate);
- 2. Air temperature at the outlet of the drying chamber (T_E) , which measures the energy wasted by the drying chamber.

We run validation cases to increase the heat supply (by increasing T_H) and vary the initial moisture content (u_0) and external temperature (T_0) of the wet solid (see values in Table A3). Compared to the experimental observations (Figure 5), the mean percent error (MPE) of the predicted u_f and T_E are 5.5% and 7.1%, respectively. These values are consistent with the MPE of numerical simulations available from References [34,35,52].

The second validation part investigates the accuracy of TFMM after changing the operating conditions of the reference cycle. We compared the simulation results with three

further experimental datasets obtained from Reference [53] and Reference [54] who studied rice drying at higher T_H and feed rate (\dot{m}_s) and at a lower airflow rate (\dot{m}_a) than the reference case study, and from the research of Reference [55] who performed an experimental analysis of drying municipal sewage sludge (MSS) (see values in Table A4). These studies measured only u_f values, and the simulation results (Figure 6a,b) showed high accuracy of the TFMM when it runs off-design conditions; for rice drying, the u_f values presented a mean percent error (MPE) of 1.5% and 4.8%; the mean error of MSS drying is approximately 5.1%.



Figure 5. Simulation vs. experimental data: u_f (**a**) and T_E (**b**) of the case study; values on the dot lines represent a prediction error of $\pm 10\%$.



Figure 6. Value of u_f under off-design conditions of rice (**a**) and MSS (**b**); values on the dot lines present the prediction error of ±10%.

5. Off-Design Analysis Setup

Our analysis involves a case study under off-design conditions; we start by simulating the baseline scenario as in the experiments, and then, we vary the operative conditions and cycle configuration to optimize its performance and reduce environmental effects. We upgraded the baseline scenario thrice—each one running 4 different combinations, named *set*, of operative conditions, for a total of 16 different setups—and compared the results.

5.1. Operating Conditions

All sets are listed in Table 1. The set1 reproduces the experimental conditions of the case study; in set2, the system dries a higher amount of rice at a higher drying temperature; thus, we investigated the effects of increasing the total mass and energy supplied to the drying chamber. The drying conditions of set3 are the same as those of set1. However, set3 operates in a colder and more humid season. Finally, we investigated the drying of a different product, the MSS, by running set4. The k, n parameters (i.e., Page's model constants) are specific for each material and vary by the drying conditions; further details about the calculation of these parameters in each set are given in the Appendix A.

Table 1. The drying conditions of each set: T_0 and T_H are the external and drying air temperature; \dot{m}_a and \dot{m}_s are the mass flow rates of the drying air and product; the terms u_0 and ω_0 measure the initial moisture content within the product and drying air and are expressed in kg of water on kg of dry matter.

SET	<i>T</i> ₀ [<i>K</i>]	<i>u</i> ₀	ω ₀ -	$\dot{m}_a [rac{kg}{s}]$	$\dot{m}_s [rac{kg}{s}]$	<i>T_H</i> [<i>K</i>]	Material	k,n
1	300	0.3	0.011	10.98	2.36	363	Rice paddy	0.103 (k) 0.771 (n)
2	300	0.3	0.011	12.86	4.17	388	Rice paddy	0.166 (k) 0.695 (n)
3	288	0.5	0.008	10.98	2.36	363	Rice paddy	0.103 (k) 0.771 (n)
4	300	0.3	0.011	10.98	$4 imes 10^{-4}$	363	MSS	1.72×10^{-6} (k) 1.487 (n)

5.2. Heat Recovery by Scenario 1

The baseline scenario is an open cycle. The exhaust air is sensibly far from the dew point (experimental observations show a minimum $T_E \approx 330$ K and maximum relative humidity of approximately 6%); thus, the system expels evaporated moisture and a sensible heat fraction to the environment, which is unexploited by the drying process.

Waste heat is a crucial indicator of the energy performance of the system because it measures the energy productively invested in the evaporation processes (i.e., drying efficiency); moreover, the heat released in the environment is one of the leading environmental affects a thermal system [56]. To decrease heat wastage, we include a heat-recovery unit in the baseline scenario; this component exploits the wasted heat to reduce the thermal load of the combustion chamber.

The result is Scenario 1 (Figure 7), in which the airflow from the drying chamber recirculates to preheat the fresh air intake by HE1; the latter is a cross-flow and air-to-air heat exchanger, configured as a tube bank and fabricated by aluminum tubes with an inner diameter of 7.5×10^{-3} m and a shell thickness of 2×10^{-3} m (Figure 8a,b).

5.3. Heat and Mass Recovery by Scenarios 2 and 3

A form of environmental effect of a drying system is the emission of pollutants in the atmosphere caused by processing hazardous materials. For example, References [12,57,58] showed that drying MSS, agricultural wastes, and biomass emits VOC, NH₃, and CO, thereby affecting the local air quality and contributing to greenhouses gas emissions.

Scenarios 2 and 3 reduce the emission of air pollutants and mitigate the wastage of heat. After they have recovered most of the waste heat by HE1, the systems restore the drying airflow at the initial conditions and reuse it in a new cycle instead of dumping it in the atmosphere. Both systems include two separate loops, one circulating the heating and one the drying air (Figures 8b and 9a); these loops exchange heat by the air-to-air heat exchangers HE0 and HE3, configured as HE1, with tubes of the same diameter and wall thickness. An external combustion chamber generates the driving heat. Its combustion

exhausts are at a fixed temperature ($T_{H'}$) of 500 K, and they feed HE0 to heat the drying air to the target temperature (T_H). When the drying process is completed and HE1 has recovered most of the wasted heat, the systems restore the initial conditions of drying air using the following steps.

- Air cooling (restoration of the absolute humidity by dehumidification)
- Air post-heating (restoration of the temperature and relative humidity).

As shown in the analysis of other air-handling systems (e.g., desalination [59]) and as confirmed by our results, the dehumidification of humid air represents an intensive energy use and entropy source. The rate of the entropy generation of a dehumidifier varies between the saturation and condensation steps because of the effect of the preponderant heat and mass transfer mechanism. As claimed by the theorem of the equipartition of entropy production [60], it is minimal when its distribution in space approaches uniformity.

To simulate air dehumidification, the TFMM solves the saturation and the condensation steps separately by calculating the state variables of the humid air along the length of the dehumidifier (*x*-direction). Thus, by comparing two cooling systems characterized by different cooling rates, costs, and heat\mass transfer mechanisms, we can choose the best technique that minimizes entropy generation.

- Scenario 2 uses HE2, a serpentine tube bank made of aluminum tubes with the same dimensions (tube diameter and thickness) as those of the air-to-air units (Figure 8c,d); this unit employs direct air cooling because a thin nonpermeable layer (tube shell) separates water from the drying air;
- Scenario 3 provides a direct-cooling system: An evaporative cooling tower which
 mixes the nebulized cooling water and the airstream in a counter-current flow; the
 tower diameter is 1 m. Heat exchange occurs through a porous packed bed with a
 specific surface ratio of 300 m²/m³ [61].

A chiller produces the cooling water for both units, and the heat subtracted by air cooling could feed low-temperature thermal processes (e.g., Reference [62]).



Figure 7. Scenario 1 is the first upgrade of the baseline scenario: An open cycle installed with a heat recovery unit.

Line

Lines



(c) (d) **Figure 8.** The spacing between the lines (L) and columns (C) of tube banks is equal in the horizontal and vertical direction s_x , s_y ; in air-to-air units (**a**,**b**) tubes are free and in air-to-water units (**c**,**d**) they are connected in a serpentine.

Columns

Ln



Figure 9. Closed cycles are Scenarios 2 (**a**) and 3 (**b**): An external combustion system keeps the chemical composition of the drying air unaltered; the latter is regenerated at the initial conditions by a cooling and a post-heating unit.

5.4. Performance Indicators

As energy efficiency indicators, we use the drying efficiency η_{dc} , which relates the heat fraction effectively used by the evaporation process to the total heat supplied to the drying chamber; also, we use the specific thermal energy consumption (STEC) and specific electric energy consumption (SEEC) to obtain the first distinction of the nature of input energies.

$$\eta_{dc} = \frac{q_{ev}}{\dot{E}_{th}} \tag{18}$$

$$SEEC = \frac{\dot{E}_{el}}{\dot{m}_{ev}} \tag{19}$$

$$STEC = \frac{\dot{E}_{th}}{\dot{m}_{ev}}.$$
(20)

The exergy efficiency η_{ex} depends on the total exergy inputs of the running cycle (i.e., the exergy of fuel $\dot{E}x_f$) and the exergy effectively invested in the drying process ($\dot{E}x_{ev}$):

$$\eta_{ex} = \frac{Ex_{ev}}{\dot{E}x_f}.$$
(21)

The fuel exergy $\dot{E}x_f$ includes the fan power, enthalpy of the reaction of the fuel, and chiller power inputs. The term $\dot{E}x_{ev}$ measures the exergy change of the amount of water that passes from the initial liquid state to the dispersed vapor state [17]. Assuming the wet product entering into the drying chamber at the dead state ($ex_{2,0}$), the term $\dot{E}x_{ev}$ depends on the exergy of the exhaust air collected at the outlet of the drying chamber ($ex_{1,E}$).

$$Ex_f = \dot{m}_{CH_4} \Delta H^0_{f,CH_4} + E_{el} \tag{22}$$

$$\dot{E}x_{ev} = \dot{m}_{ev}(ex_{1,E} - ex_{2,0}).$$
 (23)

The exergy efficiency as defined in the Equation (21) measures the effects of different drying conditions and system setup on the drying process; further, it compares the exergy costs for recovering the residual exergy of the drying exhausts (i.e., the air outflow of the drying chamber).

Finally, the exergy destruction ratio y_k measures the weight of the exergy destruction by the irreversibilities of the *k*-component ($\dot{S}_{irr,k}$) in a system formed by a total of *n* components:

$$\dot{\mathsf{E}}x_{d,k} = T_0 \dot{S}_{irr,k} \tag{24}$$

$$y_k = \frac{Ex_{d,k}}{\sum Ex_{d,k}}.$$
(25)

The parameter y_k identifies the *k*-component affected by the largest irreversibility, and it can address the designer toward the most effective design strategies for enhancing the system's performance by replacing single components.

6. Results and Discussion

This section discusses the results of the analysis by comparing the 16 simulation cases. Each case involves a specific configuration of the drying cycle running an operative *set*.

6.1. Heating and Flowing Loads

Loads of fan(s) and combustion chamber are shown in Figure 10.

Fans balance the system's pressure losses, and therefore, their power loads increase by adding a heat exchanger to the baseline layout. The average power load of the baseline scenario augments by 3 times in Scenario 1 and 7 and 6 times in Scenarios 2 and 3. The airflow rate (m_a) affects the fan power load: from *set*1 to *set*2, the average load increases by 31%; the other *sets*, where m_a is unvaried, presents slight differences caused by different dimensions (i.e., pressure drop) of the heat exchangers.

In the baseline scenario, the thermal loads are equal to the total heat supplied to the drying chamber: from *set*1, it increases by 47% in *set*2 because of the higher drying temperature and mass flow rate (T_H , \dot{m}_a) and by 7% in *set*3 because of the colder external air. Comparing the baseline scenario to Scenario 1, we observe that the heat-recovery successfully reduces thermal loads by 14%, below the operating conditions of the *set*2, up to 27% in *set*1. Closed cycles need more thermal energy than the baseline scenario because of the external combustion chamber and the post-heating process; their thermal load is three times higher than that of the baseline scenario running *sets*1, 2, *and* 4; the *set*3 produces a further increase (+6%) because of the lower temperature of feeding air (T_0).



Figure 10. The heating (red) and flowing loads (green).

6.2. Drying

Figure 11 shows a plot of the spatial distribution along the bed length of the most relevant operative parameters of the drying chamber; these results show the influence of the operating conditions on the drying process and product quality. In all simulations, the evaporation rate (\dot{m}_{ev}) gradually reduces to zero because the moisture content of the wet product tends to equilibrium levels (u_{eq}). Furthermore, \dot{m}_{ev} is inversely proportional to the material-specific resistance, which is represented by the exponential term in Page's evaporation model [63].

The results of *set2* show that the evaporation rate is augmented with the mass and energy supplied to the drying chamber: m_{ev} of *set2* is 86% higher than that of *set1*, although the final product moisture is almost the same ($u_f = 0.25$). Thus, a hotter airflow reduces u_{eq} and evaporates a more in-depth moisture layer, enhancing the drying efficiency η_{dc} (+1% as shown in Figure 12).

As shown by *set3*, the initial product moisture has a critical effect on the evaporation rate and drying performance. A more humid product presents a lower resistance to the evaporation; thus, when more humid rice is fed into the drying chamber, the thermal load of *set1* produces 2.5 times higher \dot{m}_{ev} and the η_{dc} increases up to 18%.

Finally, *set*4 showed that the nature of the processed material is the most significant parameter in the design of a drying system. The mass flow rate \dot{m}_s must decrease by

 10^3 times to reduce the moisture content of municipal sewage sludge (MSS) at the same level of rice; this inevitably reduces the \dot{m}_{ev} (10^{-2} times lower), and the drying efficiency falls below 0.3%, which indicates the current dimensions of the drying chamber are inadequate for drying MSS.

The results above are solutions of the baseline scenario, where the specific humidity of drying air at the inlet of the drying chamber is higher than the outdoor level because of the water vapor generated by methane combustion ($\omega_H > \omega_0$). This is an adverse effect of open cycles that can reduce the evaporation rate (i.e., the air humidity is closer to the equilibrium level). As shown in Figure 13, ω_H is augmented with the thermal load: comparing the Baseline systems, it increases from the external level by 27% in *set1* and by 38% in *set2*. These proportions decrease in Scenario 1 to 22% and 33%, respectively, because of the heat recovery. In general, ω_H varies between the limit calculated for the baseline scenario and those of the closed cycles, where the external combustion maintains $\omega_H = \omega_0$ (within the colored fields of Figure 13). Although the effects of ω_H on product moisture are negligible in the analyzed systems (see *u* in Figure 13), these could become significant in larger-scale systems, where the designer must adjust the drying temperature considering airflow rate.



Figure 11. Moisture content of the product (**a**), air temperature (**b**), absolute humidity (**c**), and cumulative evaporation rate (**d**) along the bed length.



Figure 13. Effects of combustion on the u and ω values compared among different sets and scenarios.

6.3. Heat Exchangers

This section discusses how the heat and mass recovery units change their size based on cycle configuration and operative conditions. The total heat exchange surfaces ($\sum \Delta A_{he}$) are shown in Figure 14; these surfaces vary as a function of the design targets, initial conditions of entering flows (temperature regimes in Table 2), and the mass and energy exchange technique (transfer coefficients in Table 3).

6.3.1. Heat Recovery

HE1 (Figure 7) pre-heats the external air intake by 10K (design target), and its total surface depends on the initial temperature of the entering streams: the airflow from the drying chamber (T_E) and that compressed by the fan (T_F). Further, the HE1 dimensions change with $\Delta T = T_E - T_0$, which measures the total heat wasted by the cycle. At a given dead-state temperature, a higher T_E reduces HE1: from *set*1, its average surface decreases

by 26% in *set*2 and by 13% in *set*4 (T_E values in Figure 11). When running *set*3, ΔT remains higher than that in *set*1, and the average surface of HE1 decreases by 8%.

The effects of T_F become evident when different scenarios that run the same *sets* (the T_E remains constant) are compared: when T_F increases because of a larger energy dissipation from the fan, the HE1 area is diminished (by approximately 1.8% per unit temperature). Based on these results, the sizes (i.e., economic costs) of heat-recovery are strictly related to the cycle performance. When the drying efficiency η_{dc} decreases, the system wastes more energy, and a smaller HE1 fulfills the design targets.

6.3.2. Mass Recovery

HE0 (Figure 9) heats the drying air from T_P to the target value T_H by combustion exhausts at 500 K. Hence, its size depends on the target heat-transfer rate, given by $\Delta T = T_H - T_P$. A higher ΔT entails a larger HE0. The average surface of *set*1 increases by 2.5 times in *set*2, when T_H is augmented, and by 24% in *set*3, when the external air gets colder. No differences were observed by running *set*4. As observed for HE1, the drying systems need a smaller unit to fulfill the target T_H when T_P increases because of the effect of more powerful compression (the HE0 area reduces by approximately 2% per unit temperature).

The cooling units are the largest ones. Below the same dead-state conditions, dimensions increase with the heat supply (i.e., heat to dissipate)—from *set1* to *set2*, the HE2 area increases by 41%, and the tower area increases by 37%. When it is difficult to dry the product and the \dot{m}_{ev} decreases, air-cooling is less demanding, and the HE2 reduces from *set1* to *set4* by 16%, while the tower dimensions do not change. The dead-state conditions produce the most significant variations on the exchange surfaces: From *set1* to *set3*, the area of the HE2 and tower increases by 85% and 48%, respectively.

Based on the results above, the dimensions of the cooling units depend on the heat supply, dead-state conditions, and nature of dried materials; these operative conditions can be defined as follows:

- Sensible heat to dissipate in the saturation step (i.e., wasted heat unrecovered by HE1);
- 2. Amount of moisture to condense, which is set equal to \dot{m}_{ev} (i.e., target heat\mass-transfer rate).

Although these quantities are interdependent (e.g., a lower m_{ev} corresponds to higher wasted heat), we can recognize which parameter has the largest influence because the TFMM calculates the cooling-rate of the saturation and the condensation step separately (see Figure 15):

- Air-saturation takes most of HE2, but its incidence on the total exchange area is more sensible to \dot{m}_{ev} than to the wasted heat: from 70% of *set*1, it decreases to 64% in *set*2, although the highest heat waste occurs, and to 36% in *set*3, where the wasted heat is only 2% less than that in *set*1 but \dot{m}_{ev} is more than double; in contrast, the air-saturation needs almost the whole HE2 in *set*4, where $\dot{m}_{ev} \approx 0$;
- The cooling tower is more efficient than HE2 because it fulfills the design targets by a smaller surface (\sim 10 times). The air saturation is almost instantaneous, and as in HE2, the m_{ev} has the largest effect on its incidence on the total tower surface. From 11% of *set*1, it decreases to 7.6% in *sets*2 and 7.9% in *set*3.

The results above show that the target m_{ev} is the most influencing parameter on the dimensions of cooling units. This is because the cooling rate is generally higher in the saturation than in the condensation step (Slopes of curves in Figure 15); therefore, an increase of m_{ev} augments the surface needs, while the wasted heat has a secondary effect in indirect cooling and becomes irrelevant in direct cooling.

An indicator that includes both \dot{m}_{ev} and the wasted heat is the drying efficiency η_{dc} . When it is augmented, systems need a large cooling unit; thus, it is similar to the

observation for HE1, and air recirculation becomes more convenient when the product is difficult to dry and the drying efficiency is low.

HE3 is the smallest unit, and its dimensions depend on the target heat-transfer rate, given by the temperature difference $\Delta T = T_D - T_0$ as well as the inlet temperature $T_{P'}$ of the combustion exhausts. In particular, the HE3 area decreases when the dead-state\target conditions (T_0 , ω_0) are reduced and it is augmented with the heat demand because $T_{P'}$ reduces when more heat is taken from the combustion exhausts: from *set*1, the exchange area increases by 46% in *set*2, decreases by 69% in *set*3, and remains constant in *set*4.



Figure 14. Total exchange surfaces varying among the different sets and scenarios.

Table 2. The inlet and outlet temperatures of the heat exchangers.

SET	T	Scenario 1		Scenario 2				Scenario 3			
SEI	Temperature [K]	HE1	HE0	HE1	HE2	HE3	HE0	HE1	СТ	HE3	
	T1,in	357.50	314.70	357.60	347.60	288.75	313.90	357.60	347.60	288.70	
CET1	T1,out	347.50	363.15	347.60	288.75	300	363.15	347.60	288.70	300	
SEII	T2,in	302.50	500	304.70	280.15	451.90	500	303.90	280.15	451.12	
	T2,out	312.50	451.90	314.70	284.87	440.65	451.12	313.90	284.85	439.83	
SET2	T1,in	378.81	314.43	379.12	369.20	288.76	313.50	379.12	369.20	288.70	
	T1,out	368.90	388.15	369.20	288.76	300	388.15	369.20	288.70	300	
	T2,in	302.77	500	304.43	280.15	414.25	500	303.49	280.15	413.16	
	T2,out	312.77	414.25	314.43	287.72	403	413.15	313.49	287.53	401.86	
	T1 <i>,</i> in	348.73	302.81	348.88	339.05	283.87	301.82	348.87	338.87	283.84	
CET2	T1,out	338.85	363.15	338.98	283.86	288	363.15	338.97	283.83	288	
SEIS	T2,in	290.21	500	292.81	280.15	440.10	500	291.82	280.15	439.12	
	T2,out	300.21	440.10	302.81	284.58	435.98	439.12	301.82	284.57	434.96	
	T1 <i>,</i> in	362.79	314.27	363.01	353.01	289.35	313.77	363	352.74	288.70	
SET4	T1,out	352.81	363.15	353.01	289.35	300	363.15	353	288.70	300	
	T2,in	302.30	500	304.26	280.20	451.46	500	303.77	280.15	450.96	
	T2,out	312.30	451.45	314.26	285.27	440.81	450.96	313.77	285.25	439.67	

SET		Scenario 1	Scenario 2				Scenario 3			
	Coefficients	HE1	HE0	HE1	HE2	HE3	HE0	HE1	СТ	HE3
SET1	HTC [W/m ² K]	9.30	9.01	9.30	8.34	9.26	9.01	9.30	126.80	9.26
	MTC [m/s]	-	-	-	0.0063	-	-	-	0.096	-
SET2	HTC [W/m ² K]	9.73	8.56	9.73	8.35	9.69	8.56	9.73	136.19	9.69
	MTC [m/s]	-	-	-	0.0063	-	-	-	0.103	-
SET3	HTC [W/m ² K]	9.31	9.01	9.30	7.97	9.26	9.01	9.30	127.05	9.26
	MTC [m/s]	-	-	-	0.0060	-	-	-	0.096	-
SET4	HTC [W/m ² K]	9.29	9.01	9.29	8.02	9.26	9.01	9.29	126.75	9.26
	MTC [m/s]	-	-	-	0.0060	-	-	-	0.096	-

Table 3. The heat and mass transfer coefficients of the heat exchangers.



Figure 15. The temperature difference between two phases inside HE2 and the cooling tower (CT); the dew point (red point) separates the saturation from the condensation step: SET1 (**a**), SET2 (**b**), SET3 (**c**), and SET4 (**d**).

6.4. Thermodynamic Performance

We show the variations in the thermodynamic performances of a drying cycle among different *sets* and configurations. The designer can assess the productivity and the convenience of the operating conditions based on specific energy consumptions and second law indicators defined in Section 5.4.

6.4.1. Specific Energy Consumptions

Figure 16 shows the specific electric and thermal energy consumptions. HE1 reduces the heat demand by pre-heating the feeding air of the combustion chamber, but it increases the electrical needs by additional pressure losses. From baseline to Scenario 1, the STEC decreases at least by 14% below the operating conditions of the *set*2 and up to 27% under the *set*1; the average SEEC augments by 3 times.



Figure 16. Specific electric energy consumption (SEEC) (**a**) and the specific thermal energy consumption (STEC) (**b**) collected by operative sets.

The energy needs of closed cycles increase because of the effect of the additional pressure drops and the energy demand of the processes for air recirculation. From the values of the baseline scenario, the average STEC increases by 3.2 times because of the

external combustion and air post-heating; the average SEEC increases by 27 times owing to the electricity needs of the heat-pump feeding cooling units.

When a *set* improves η_{dc} , it reduces the energy consumptions: from *set*1 to *set*2, the average SEEC and STEC decrease by 19% and 39%, respectively; *set*3 performs the best because it reduces the SEEC by 63% and the STEC by 57%. *Set*4 performs the worst, and it augments both indicators by approximately 40 times.

When comparing the single *set*-Scenario, it becomes clear how the SEEC and STEC describe the effects of the operating conditions on the system configuration and its final energy consumption: for example, from Baseline to Scenario 1, the STEC diminishes by 27% below *set*1 and by 31% below *set*2; the SEEC increases by 3.4 times in *set*1 and by 2.8 times in *set*2. Thus, the benefits of the heat-recovery are more conspicuous in *set*2 than in *set*1 because an increase of the thermal load augments the η_{dc} , and simultaneously, it reduces the dimensions of HE1 with related pressure drops.

6.4.2. Irreversibility and Exergy Efficiency

The exergy efficiencies (η_{ex}) and the exergy destruction rates ($\dot{E}x_d$) with the ratios of system components are shown in Figures 17 and 18.

The effects of methane and electricity consumption on exergy efficiency are evident when comparing the different cycles. From the baseline scenario, the average η_{ex} increases by 15% in Scenario 1 because of heat recovery, whereas it reduces by 64% in closed cycles, characterized by the highest exergy inputs. On the total $\dot{E}x_d$, the incidence of the fan is generally irrelevant (\approx 1%), whereas the combustion chamber plays the most significant role (90–80%). The primary entropy source of air-heating is the combustion reaction; therefore, $\dot{E}x_{d,CC}$ is augmented with fuel consumption: its average value in the baseline scenario decreases by 20% in Scenario 1, and it is augmented by 2.2 times in closed cycles.

The exergy performances of the drying chamber follow the drying efficiency (see η_{dc} in Figure 12). The average η_{ex} is augmented by 70% from *set1* to *set2* and by 1.2 times in *set3*; $\dot{E}x_{d,DC}$ of *set1* is doubled in *set2* and is augmented by 2.5 times in *set3*. Both parameters are decreased by more than 10 times when *set4* is run. When it is difficult to dry the product or the bed dimensions are inappropriate, a shorter amount of exergy is invested in the evaporation process. In contrast, a higher heat supply or more favorable dead-state conditions enhance the exergy efficiency by augmenting m_{ev} .



Figure 17. Exergy efficiency among different sets and scenarios.



Figure 18. Exergy destroyed in different cycles by flowing (Fan1-Fan2), heating (CC), drying (DC), and heat and mass recovery (HE-CT) processes.

All heat exchangers are additional entropy sources that contribute to the total exergy destruction. The entropy generation of these components depends on their respective heat and mass transfer mechanisms, as well as the specific design targets. No mass transfer occurs within the air-to-air units; therefore, their entropy generation exclusively depends on the inlet temperature difference between the airflows and the target heat-transfer rate:

• HE0 is the air-to-air unit with the highest destruction ratio ($y_{HE0} \approx 5\%$); results show that $\dot{E}x_{d,HE0}$ is augmented with the heat-transfer rate (given by $\Delta T = T_H - T_P$). Its average value below *set*1 increases by 3 times in *set*2 and by 1.5 times in *set*3, and it remains unvaried in *set*4.

- HE1 is the heat exchanger with the lowest exergy destruction rate, and its influence on the total $\dot{E}x_d$ is insignificant ($y_{HE1} < 0.5\%$). $\dot{E}x_{d,HE1}$ increases with energy wastage (derived by temperatures T_E, T_F): its average value is augmented by 50% from *set*1 to *set*2, by 18% in *set*3, and 16% in *set*4.
- The destruction ratio of HE3 is similar to that of HE1. $\dot{E}x_{d,HE3}$ depends on the heattransfer rate: from *set*1 to *set*2, it is diminished by 15%, and in *set*3 by 63%. Thus, it is diminished when $T_{P'}$ is lowered or the dead-state temperature reduces.

The entropy generation of the cooling units depends on the initial humidity and temperature of the airflow and the target cooling-rate; their respective $\dot{E}x_d$ changes by the cooling technique, and it is different between the saturation and the condensation steps (see Figure 19).



Figure 19. Spatial distribution of exergy destruction rate within HE2 (purple) and cooling tower (blue); the dew point (red point) separates the saturation from the condensation step: SET1 (**a**), SET2 (**b**), SET3 (**c**), and SET4 (**d**).

- HE2 is the heat exchanger characterized by the highest destruction ratio ($y_{HE2} \approx 26\%$). As shown in Figure 19, most of the exergy destruction occurs in the saturation step; $\dot{E}x_{d,HE2}$ doubles from *set1* to *set2* and increases by 10% in *set4* where the condensation is almost instantaneous ($\dot{m}_{ev} \approx 0$).
- The cooling tower reduces the irreversibility of air-cooling: the destruction ratio is $y_{CT} = 15\%$, and with respect to HE2, the exergy destruction generally decreases by half. In terms of exergy destruction, 90% occurs in the condensation step, and the total $\dot{E}x_{d,CT}$ doubles in *set*2 and is augmented by 20% in *set*4, while it shows no changes in *set*3.

Waste heat is the primary entropy source of air-cooling. When the temperature of the inlet air (T_C) increases, it extends the saturation step where the exergy destruction occurs at a faster rate. Finally, for each cooling-unit, we calculate the standard deviation (σ) of its respective exergy destruction rate. This parameter measures the spatial distribution of entropy generation (a lower variance corresponds to a more homogeneous distribution), as shown in Reference [64]. Data reported in Figure 19 show that the unit that destroys more exergy presents the highest variance of exergy generation rate; thus, our results verify the theorem of equipartition of entropy production [60].

6.5. Climate Effects

The dead-state conditions have a significant effect on the evaporation rate and on the performance of the entire drying cycle (see Section 6.2). Therefore, we present a reduced solution of TFMM, focusing on the effects of climate on the exergy efficiency of the baseline scenario. Based on these results, we propose some adjustments to be made to the operative conditions to stabilize the production target (the final product moisture u_f) in terms of yearly climatic variations.

Figure 20 shows the η_{ex} of the baseline scenario, calculated below the Brescia climate year 2018, on a monthly scale. The dried product is rice paddy, and the initial moisture content is 0.7 in season 1 (from November to May) and 0.6 in season 2 (from June to October). The system is initially running *set1* (data label is $E_{th} = 1$ in Figure 20): η_{ex} varies along the year ($\pm 2\%$ on average), and it is the maximum in the colder season. The u_f never falls in the set target region (the green field, where $u_f = 0.5 \pm 0.02$), indicating that the current energy supply is inadequate. As a solution, we double the heat supply when the system is undersized and reduce it by 25% when over-sizing; the results show an enhancement of η_{ex} in all months by +21% on an average in season 1 and +13% in season 2 and stabilization of the final u_f in the target region.



Figure 20. The exergy efficiency and final moisture content of the baseline scenario in the Brescia climate year 2018 at different operating conditions; starting from inputs of set1 (data in purple), we doubled (data in red) and reduced by 25% (data in orange) the thermal loads.

7. Conclusions

The performance of convective drying systems depends on a wide range of interrelated operating parameters that affect the energy use, exergy efficiency, dimensions (i.e., costs) of system components, and product quality. We proposed a methodology that calculates the system performance considering exogenous variables (climatic conditions, initial product moisture, and physical properties of the dried product), energy\mass intake, and cycle configuration.

On comparing the results of different *sets* to the reference *set*1, the evaporation rate showed the most significant effect on the global performance because it determines the energy and exergy productively invested in the drying process. When increasing heating and flowing loads (*set*2), the system evaporates a deeper moisture layer with benefits on the exergy efficiency (+97%). Higher initial product moisture (*set*3) augments the evaporation rate, and the drying cycles presents the best performance in terms of drying efficiency (+114%) and exergy efficiency (+127%). When drying the MSS (*set*4), the evaporation rate reduces by approximately 10^2 times, worsening the exergy performance (-97%); such results reveal the dimensions of the drying bed inadequate to dry that particular product.

Scenario 1 is the optimal system configuration. The heat-recovery increases the baseline electrical consumption and reduces the thermal consumption by maximum +211% and -17%, respectively, with benefits on the exergy efficiency (+17%). The efficiency of heat recovery depends on the wasted energy; at low drying efficiency, or when the fan dissipates more shaft work, the HE1 fulfills the production target reducing the exchange surface by 25%. Thus, the heat-recovery is more convenient in low efficiency processes when the material is difficult to dry.

Closed cycles cut the exergy efficiency by maximum -67%. These systems use four additional heat exchangers increasing the electric consumption by 20 times. Moreover, external combustion and air regeneration processes augment the thermal energy needs (+180%). The performances of Scenario 3 are slightly better than that of Scenario 2 because the tower presents a faster cooling-rate than HE2, especially in the saturation step. This process occurs almost instantaneously in the tower that reaches the target cooling conditions with a 10 times smaller surface than HE2. Furthermore, when the saturation step becomes shorter, the total exergy destruction rate diminishes (-48%), and its spatial distribution tends to become more uniform (-39%). Thus, the tower reduces system irreversibility.

Based on the above results, we derive some technical recommendations that can help the designer optimize the energy and exergy use of a convective drying system.

- The performance of the system varies along the climatic year because of the variations
 of the initial temperature and humidity of the working flows (air intake and processed
 product). However, the designer can ensure the production targets are unaltered by
 adjusting the energy input with benefits on the exergy efficiency. Best performances
 are observed in the cold season.
- Operating conditions shall be oriented to maximize the evaporation rate; the increasing thermal loads is valid to this purpose; however, it is limited by some adverse effects as the depletion of the product quality and the humidification of drying air by combustion. As an alternative, the designer can augment the dimensions of the drying bed and extend the residence time of the processed product in the drying chamber.
- When the bed cannot be enlarged, the drying efficiency is low, and a heat recovery unit can reuse a fraction of the heat wasted by the drying chamber to preheat the external air intake; this practice is particularly advantageous in high-temperature processes where small units significantly increase energy and exergy efficiency.
- Air recirculation dramatically reduces the performance of the system because of air regeneration processes. More than an optimization practice, the cycle closure can be a safety procedure for drying hazardous materials and limit the emissions of harmful substances in the environment. The cooling tower is particularly suitable for this purpose; compared to an indirect cooling system, it presents the highest energy and exergy efficiency and is configurable as a wet scrubber to wash away toxic species from the airflow and restore its initial conditions.

Future developments will overcome the limitations of the current work. Using a real gas model (e.g., Van der Walls), the TFMM can simulate the compression and throttle

of a refrigerant fluid and predict the performances of a drying cycle driven by the heat pump, thereby promising remarkable enhancement of the exergy efficiency caused by the low-temperature of the heat generation process. Finally, the coupling of the TFMM to an analytical model (e.g., upscaled porosity model) will increase the accuracy of TFMM to describe the drying phenomenology and simulate the process at a higher level of detail.

Appendix A

Appendix A.1. Equations of State

The state functions of Phase 1 are calculated on a molar basis using the molar mass M_{1j} of single j-species:

$$\dot{m}_1(\epsilon_{1j}) = \sum_{j=1}^r \left[\frac{\alpha_1 \epsilon_{1j} \dot{m}_{os}}{M_{1j}} \right] = \sum_{j=1}^r [\dot{n}_{1j}]$$
(A1)

$$\dot{H}_{1}(\epsilon_{1j},T) = \sum_{j=1}^{r} \left[\frac{\alpha_{1}\epsilon_{1j}h_{1j}\dot{m}_{os}}{M_{1j}} \right] = \sum_{j=1}^{r} [\dot{n}_{1j}h_{1j}]$$
(A2)

$$\dot{S}_1(\epsilon_{1j}, T, P) = \sum_{j=1}^r \left[\frac{\alpha_1 \epsilon_{1j} s_{1j} \dot{m}_{os}}{M_{1j}} \right] + S_{mix} = \sum_{j=1}^r [\dot{n}_{1j} s_{1j}] + S_{mix}$$
(A3)

$$S_{mix}(\epsilon_{1j}) = -R \sum_{j=1}^{r} \left[\dot{n}_{1j} ln(\epsilon_{1j}) \right]$$
(A4)

$$\dot{E}x_1(\epsilon_{1j}, T, P) = \sum_{i=1}^r \left[\frac{\alpha_1 \epsilon_{1j} e x_{1j} \dot{m}_{os}}{M_i} \right] = \sum_{j=1}^r [\dot{n}_{1j} e x_{1j}].$$
(A5)

The term S_{mix} is the entropy of mixing; the specific state functions h_{1j} and s_{1j} are calculated assuming the specific heat of each r-species as a polynomial T-dependent; the values of constants a_{1j} , b_{1j} , c_{1j} , and d_{1j} are listed in Tables [49]:

$$c_{p,1j}(T) = a_{1j} + b_{1j}T + c_{1j}T^2 + d_{1j}T^3$$
(A6)

$$h_{1j}(T) = \int_{T_0}^T [c_{p,1j}(T)] dT = \left[a_{1j}T + \frac{b_{1j}}{2}T^2 + \frac{c_{1j}}{3}T^3 + \frac{d_{1j}}{4}T^4 \right]_{T_0}^T,$$
 (A7)

$$s_{1j}(T,P) = \int_{T_0}^T \left[\frac{c_{p,1j}(T)}{T}\right] dT - \int_{P_0}^P \left[\frac{R}{P}\right] dP = \left[a_{1j}ln(T) + b_{1j}T + \frac{c_{1j}}{2}T^2 + \frac{d_{1j}}{3}T^3\right]_{T_0}^T - \left[Rln(P)\right]_{P_0}^P.$$
 (A8)

Within the air-to-air heat exchangers, Phase 2 is a mixture of gaseous species, and its state functions are derived by the equations above. In all other components, Phase 2 is a mixture of solid and/or liquid species, and the state functions are calculated as follows:

$$\dot{m}_2(\epsilon_{2j}, T) = \sum_{j=1}^k [\alpha_2 \epsilon_{2j} \dot{m}_{os}] = \sum_{i=1}^k [\dot{m}_{2j}]$$
 (A9)

$$\dot{H}_{2}(\epsilon_{2j},T) = \sum_{j=1}^{k} [\alpha_{2}\epsilon_{2j}\dot{m}_{os}h_{2j}] = \sum_{i=1}^{k} [\dot{m}_{2j}h_{2j}]$$
(A10)

$$\dot{S}_{2}(\epsilon_{2j},T) = \sum_{j=1}^{k} [\alpha_{2}\epsilon_{2j}\dot{m}_{os}s_{2j}] = \sum_{i=1}^{k} [\dot{m}_{2j}s_{2j}]$$
(A11)

$$\dot{E}x_2(\epsilon_{2j},T) = \sum_{j=1}^k [\alpha_2 \epsilon_{2,i} \dot{m}_o sex_{2j}] = \sum_{i=1}^k [\dot{m}_{2j} ex_{2j}],$$
(A12)

where h_{2j} and s_{2j} are calculated assuming a constant specific heat of each k-component (values are found in References [47–49]):

$$c_{p,2j}(T) = a_{2j}$$
 (A13)

$$h_{2j}(T) = \int_{T_0}^T [c_{p,2j}(T)] dT = a_{2j} \Big[T \Big]_{T_0}^T$$
(A14)

$$s_{2j}(T) = \int_{T_0}^T \left[\frac{c_{p,2j}(T)}{T}\right] dT = a_{2j} \left[ln(T)\right]_{T_0}^T.$$
(A15)

Finally, the specific exergy of the j-component is calculated by this general expression for both i-phases:

$$ex_{ij}(T,P) = [h_{ij}(T) - h_{ij}(T_0)] - T_0[s_{ij}(T,P) - s_{ij}(T_0,P_0)].$$
(A16)

Appendix A.2. Fan Equations

In this section, we performs adiabatic compression of a single gaseous phase, the drying air, formed by 3-species: N_2 , O_2 , H_2O . The total shaft work is a function of the air flow rate, the pressure head, and the fan efficiency $\eta_f = 0.8$

$$\dot{W}_{1}^{\leftarrow} = \frac{\dot{W}_{rev}^{\leftarrow}(\dot{m}_{1}, \Delta p_{1})}{\eta_{f}},\tag{A17}$$

where $\dot{W}_{rev}^{\leftarrow}$ refers to an ideal component when $\eta_f = 1$. The airflow rate is specific for each operative set, while Δp_1 is calculated in each scenario to balance the pressure losses of all components.

Appendix A.3. Combustion Chamber Equations

An adiabatic combustion chamber covers the heat demand of the drying cycles: after fuel injection, the airflow reaches the desired temperature by an instantaneous combustion reaction. The running set gives the outlet temperature T_H of open cycles; in closed cycles, the outlet temperature T'_H is calculated over the heat demand of both units HE0 and HE3.

The two phases processed by this unit are drying air (Phase 1) which reacts with a hydrocarbon $C_l H_n$ (Phase 2) as

$$C_l H_n + (l + \frac{n}{4})O_2 = lCO_2 + \frac{n}{2}H_2O.$$
 (A18)

The combustion products are CO_2 and H_2O , and we can neglect the formation of other components, such as CO and NO_x because of the high air excess ($\lambda > 4$) and the low operative temperatures (<1250 K) [49]. Pure methane (l = 1, n = 4, indexed by j = 1) is used as fuel, and assuming its complete combustion, the amount (per moles of fuel) of *j*-species exchanged between two phases is given by the stoichiometric coefficients v_{ij} , derived by Equation (A18):

$$\Delta \dot{m}_{12,j} = \epsilon_{21} \dot{m}_2 \nu_{ij} \frac{M_{ij}}{M_{21}} \tag{A19}$$

 M_{ij} is molar mass. The energy and the entropy exchanged by combustion are respectively calculated by the standard enthalpy and the entropy of formation [49]

$$\Delta \dot{Q}_{12,j} = \Delta \dot{m}_{12,j} \Delta H^0_{f,j} \tag{A20}$$

$$\Delta \dot{S}_{12,j} = \Delta \dot{m}_{12,j} \Delta S^0_{f,j}. \tag{A21}$$

Appendix A.4. Drying Chamber Equations

In the drying chamber, the hot air (Phase 1) crosses the wet product (Phase 2) and evaporates its liquid fraction. We neglect the heat losses across the chamber walls (adiabatic chamber), and the Ergun equation [65] gives the pressure losses of the airflow across the bed. The evaporation process is described by the Page equation:

$$MR = exp(-kt^n), \tag{A22}$$

where MR is the moisture ratio, which is defined as

$$MR = \frac{u - u_0}{u_0 - u_{eq}}.$$
 (A23)

The constants k, n depend on the nature of the product and drying conditions. In this work, we calculate the k, n values for rice paddy drying by the empirical correlations of Reference [50] given as function of the drying airflow rate (\dot{m}_a), the drying temperature (T_H), and the hold-up of drying bed. The k, n values of MSS derive from the experimental database of Reference [55], considering the appropriate drying temperature and ultrasound turned off. The thermo-physical properties of rice were taken from References [16,47,50] and those of MSS from References [12,48,66].

The moisture content (on dry basis) of the dried product along the bed is calculated by the velocity of solid flow v_2 :

$$u(x) = u_{eq} + (u_0 - u_{eq})exp(\frac{-kx^n}{v_2^n}),$$
(A24)

where u_{eq} is the equilibrium moisture content of drying air, calculated using Laithong equation [67], and u_0 is the initial moisture content of the dried product. Only water changes phases, and assuming *j*=3 for water vapor and *j*=2 for liquid water, the mass exchanged by phase transition (i.e., moisture evaporation rate) can be written in these two equivalent forms:

$$\Delta \dot{m}_{12} = (\epsilon_{11} + \epsilon_{12}) \dot{m}_1 [u(x + dx) - u(x)]$$
(A25)

$$\Delta \dot{m}_{21} = \epsilon_{21} \dot{m}_2 [u(x+dx) - u(x)].$$
(A26)

The evaporated moisture instantaneously reaches equilibrium with the air flow (perfect mixing assumption [68,69]), and because $u_{eq} \ll u_0$, the evaporation immediately starts at the chamber inlet. Hence, the heat exchanged between two phases is exclusively in the latent form:

$$\Delta Q_{12} = \Delta \dot{m}_{12} \Delta H_{fg, H_2O} \tag{A27}$$

$$\Delta S_{12} = \Delta \dot{m}_{12} \Delta S_{fg,H_2O}. \tag{A28}$$

Appendix A.5. Heat Exchangers: Modeling Approach

The current practice distinguishes two approaches for designing heat exchangers: the rating and sizing problem [70]. The latter consists of calculating the heat exchange surface that meets the target thermodynamic states of exchanging fluids: the heat exchanger setup is unknown, and the fluid temperatures and heat transfer rate are given. Our off-design analysis studies the effects on the thermodynamic performance of a reference drying system by varying the operating conditions and adding new components. Therefore, we model the heat exchangers by the sizing approach: we calculate the heat exchange surface to transform the drying air at target states. Inlet conditions and target states depend on the parameters presented in Table 1 and the specific purpose of each unit reported in following paragraphs.

Appendix A.6. Heat Exchangers: Air-To-Air Units HE0, HE1, and HE3

Air-to-air heat exchangers transfer heat between the drying air (Phase 1) and another gaseous flow (Phase 2); the moisture content and chemical mixture of both phases is different in each unit. Air-to-air heat exchangers are adiabatic and present specific inlet conditions and design target:

- HE1 preheats the compressed air by the drying exhaust. Input temperatures T_E and T_F derive from the drying chamber and fan, and the target temperature is $T_P = T_F + 10$ K (i.e., HE1 preheats the compressed air by 10*K*). The value $\Delta T = 10$ K is coherent with other works focused on heat recovery in drying system [71–73]. However, this parameter could be easily changed according to targets and limitations set by the designer: for larger ΔT , the HE1 size (costs) and benefits on global performance increase; in the opposite case, the heat recovery is cheaper, but the benefits on system performance decrease.
- HE0 heats the air to the drying temperature of the cycle by combustion exhausts (see T_H in Table 1); the inlet temperature T_P derives from HE1 and the temperature T'_H is fixed to 500 K. The temperature $T'_H = 500$ K ensures the combustion chamber to cover the heat demand of both HE0 and HE3 in all *sets*. Results show that the heating air presents a residual heat fraction when it leaves HE3, and therefore the T'_H could be reduced in future applications, promising an improvement of the closed cycle performance.
- The unit HE3 restores the initial temperature of the air. Hence, the target temperature is *T*₀ (i.e., the dead-state temperature), and no assumptions have been made for inlet temperatures that derive from the cooling units and HE0.

All air-to-air heat exchangers are banks of aluminum tubes with an inner diameter $d = 7.5 \times 10^{-3}$ m and a shell $t = 2 \times 10^{-3}$ m. The tube lenght is 3 m (along z-direction), and the spacing between two near tubes is set equal in both direction $s_x = s_y = 1.25$ d. Each column consists of fixed-line numbers *L* and is *dx* wide, and the total heat exchanged within the single column is given as:

$$\Delta \dot{Q}_{12} = U_{t,he} \Delta A_{he} (T_2 - T_1), \tag{A29}$$

where ΔA_{he} is the exchange surface of the column and $U_{t,he}$ is a constant heat transfer coefficient (HTC), which is calculated by the following resistance scheme:

$$U_{t,he} = \frac{1}{\frac{1}{k_1} + \frac{t}{\lambda_{Al}} + \frac{1}{k_2}},$$
(A30)

where *t* is the tube wall thickness, λ_{Al} is the tube shell thermal conductivity and k_1, k_2 derive from empirical correlations representing the forced convection of an air flow on a tube bank (Phase 1 side) and the forced convection of an airflow within a horizontal tube (Phase 2 side) [74]. The pressure drop across the air-to-air heat exchangers are calculated by the model of Beale for tube banks [75].

Appendix A.7. Heat Exchangers: Air-To-Water Units HE2 and Cooling Tower

The HE2 and CT are indirect and direct cooling systems, respectively. Both units are adiabatic, and they restore the dead-state moisture content of the drying air (Phase 1) by pure water flow (Phase 2); thus, the target state of these units is the moisture content $\omega_D = \omega_0$. The inlet temperature T_C derives from heat recovery, and the inlet temperature of the cooling water is fixed to 280.15 K according to values prescribed by the European standard EN 14511:2018 [76] to rate the performance of process chillers. However, the water leaving the cooling units presents a residual cooling capacity; therefore, the inlet water temperature could be reduced in future applications, promising performance optimization for closed cycles. Air cooling and moisture condensation involve heat and mass exchange, split into two subsequent steps: (i) saturation of the airflow and (ii) condensation of its

water fraction; the exchanges defined below are referred to in each step by superscripts *i* and *ii*.

HE2 is a bank of serpentine tubes with similar features to the air-to-air units (equals d, t, s_x, s_y). In this unit, the saturation occurs with no mass exchange and the total exchanged heat becomes

$$\Delta \dot{Q}_{12}^{i} = U_{t,he2} \Delta A_{he2} (T_2 - T_1), \tag{A31}$$

where ΔA_{he2} is the exchange surface of a single column and $U_{t,he2}$ is a constant HTC calculated as:

$$U_{t,he2} = \frac{1}{\frac{1}{k_{1,he2}} + \frac{t}{\lambda_{Al}} + \frac{1}{k_{2,he2}}},$$
(A32)

where $k_{1,he2}$ is the condensing side transfer coefficient (Phase 1 side), *t* is the tube wall thickness, λ_{Al} is the tube shell thermal conductivity, and $k_{2,he2}$ models the forced convection of water within a serpentine tube (Phase 2 side) [74]. By cooling the drying air, we can decrease its saturation moisture content

$$\omega_{sat} = 0.622 \frac{p_{sat}}{p_0 - p_{sat}},$$
 (A33)

where p_{sat} is given by Tetens equation [77] as a function of T_1 . When ω_{sat} is lower than the effective moisture content of drying air (Equation (A34)), the water vapor condenses and the total exchanged heat is in the sensible and latent form (Equations (A35) and (A36)):

$$\omega_1 = \frac{\epsilon_{1,3}}{(1 - \epsilon_{1,3})} \tag{A34}$$

$$\Delta \dot{m}_{12}^{ii} = U_{m,he2} \Delta A_{he2} (\omega_{sat} - \omega_1) \tag{A35}$$

$$\Delta \dot{Q}_{12}^{l_1} = U_{t,he2} \Delta A_{he2} (T_2 - T_1) + \Delta \dot{m}_{12} \Delta \dot{H}_{fg,H_2O}, \tag{A36}$$

where $U_{m,he2}$ is the mass transfer coefficient (MTC), derived from $U_{t,he2}$ by the Lewis approximations for air-water systems [78]. The HE2 is configured as a tube bank; therefore, we calculate the pressure losses of this unit by the same models used for air-to-air units [75].

The cooling tower presents a circular section with a 1m diameter. The airflow is directly mixed to the cooling water in a porous packed bed with a specific surface ratio of $300 \text{ m}^2/\text{m}^3$, and therefore an inter-phase mass and heat exchange occurs since the saturation step:

$$\Delta \dot{m}_{12}^{i} = U_{m,ct} \Delta A_{ct} (\omega_{sat} - \omega_1) > 0 \tag{A37}$$

$$\Delta \dot{Q}_{12}^{i} = U_{t,ct} \Delta A_{ct} (T_2 - T_1) + \Delta \dot{m}_{12}^{i} \Delta \dot{H}_{fg,H_2O}.$$
(A38)

The drying air is gradually saturated and cooled, and when its moisture content becomes higher than ω_{sat} , water vapor condensation occurs:

$$\Delta \dot{m}_{12}^{ii} = U_{m,ct} \Delta A_{ct} (\omega_{sat} - \omega_1) < 0 \tag{A39}$$

$$\Delta \dot{Q}_{12}^{ii} = U_{t,ct} \Delta A_{ct} (T_2 - T_1) + \Delta \dot{m}_{12}^{ii} \Delta \dot{H}_{fg,H_2O}.$$
 (A40)

The term $U_{t,ct}$ derives from $U_{m,ct}$ by the Lewis approximations. The exchange surface ΔA_{ct} in a tower element of height dx depends upon the specific surface of porous packed bed. The MTC and pressure losses of the packed bed are calculated by the empirical correlations presented by Reference [61].

Appendix A.8. Heat Exchangers: Geometrical Setup

The tables below resume the geometrical features of the tube banks and cooling tower distinguished for single *sets*.

	SET	Scen	Scenario 1		ario 2	Scenario 3		
	SEI	L	С	L	С	L	С	
	1		39		41		40	
	2	100	29	100	30	100	30	
ΠEΙ	3	100	36	100	38	100	37	
	4		34		36		35	
	1	-	-		58		59	
LIEO	2	-	-	110	142	110	144	
HEU	3	-	-	110	72	110	73	
	4	-	-		59		59	
	1	-	-		13		13	
LIE2	2	-	-	100	19	100	19	
HE3	3	-	-	100	4	100	4	
	4	-			12		13	

Table A1. The lines (L) and columns (C) of the air-to-air heat exchangers.

Table A2. The lines (L) and columns (C) of the HE2 units and the heights (H) of the cooling tower.

	CET	Scen	ario 2		CET	Scenario 3
	SEI	L	С		SEI	H(m)
HE2	1	100	41		1	1.5
	2	100	30	CT	2	2
	3	100	38	CI	3	2.2
	4	100	36		4	1.5

Appendix A.9. Validation Cas

Table A3. The validation cases of the reference drying system.

Study	Case	Dead-State Conditions			Dryi	ing Conditi	Results		
Study	Case	<i>u</i> ₀	T ₀ [K]	ω_0	$\dot{m}_a \left[\frac{kg}{s}\right]$	$\dot{m}_s \left[\frac{kg}{s}\right]$	$T_H[K]$	u _f	$T_E[K]$
	1	0.362	306.9	0.0114			363.1	0.330	332.8
	2	0.365	307.2	0.0116			363.1	0.309	334
	3	0.331	304.1	0.0009			363.1	0.282	335.8
	4	0.348	303.5	0.0009			363.1	0.306	334.9
[50]	5	0.360	303.1	0.0009	10.82	2.36	363.1	0.311	333.7
	6	0.308	304.8	0.0101			372.1	0.253	333.7
	7	0.331	300.5	0.0079			372.1	0.285	332.9
	8	0.323	300.5	0.0079			372.1	0.262	340.3
	9	0.309	300.2	0.0079			372.1	0.245	347.1
	1	0.280	305.1	0.0193			391	0.236	358
	2	0.308	304.6	0.0187			396	0.308	363
	3	0.304	304.1	0.0182			398	0.258	363
	4	0.325	304.1	0.0182			390	0.255	351
	5	0.332	305.1	0.0193			393	0.274	361
	6	0.312	304.6	0.0187			389	0.241	351
[51]	7	0.310	304.1	0.0182	10.82	2.26	393	0.243	354
[31]	8	0.275	302.1	0.0162	10.82	2.30	385	0.232	359
	9	0.282	302.1	0.0162			380	0.230	351
	10	0.281	303.1	0.0172			378	0.237	353
	11	0.289	303.1	0.0172			383	0.234	351
	12	0.280	303.1	0.0172			376	0.233	347
	13	0.292	303.1	0.0172			386	0.240	355
	14	0.280	304.15	0.0182			378	0.234	352

Study	Case	Dead-State Conditions			Dryi	ng Condit	Results		
		<i>u</i> ₀	$T_0[K]$	ω_0	$\dot{m}_a \left[\frac{kg}{s}\right]$	$\dot{m}_s \left[\frac{kg}{s}\right]$	$T_H[K]$	u _f	$T_E[K]$
[54]	1	0.218						0.194	
[54]	2	0.225	300	0.01	6 74	4 78	388 1	0.196	n.a.
	3	0.220		0101	01	1.0 0	00011	0.198	1.000
	4	0.218						0.197	
	1	0.283			12.37			0.236	
	2	0.280		0.01	11.39	4.48	418	0.235	n.a.
[53]	3	0.284	300		11.39			0.238	
	4	0.302			12.99			0.219	
	5	0.314			13.11			0.230	
	1							3.78	
	2							3.46	
	3							3.16	
	4							2.85	
	5							2.55	
	6							2.26	
	7	4	200	0.01	10.00	0.026	2(2	1.98	
[33] .	8	4	300	0.01	10.98	0.036	303	1.70	n.a.
	9							1.43	
	10							1.17	
	11							0.95	
	12							0.73	
	13							0.53	
	13							0.19	

Table A4. The validation cases on off-design conditions; (*) we reconstruct the experimental drying curve measured at $u_0 = 4$.

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